

Uncertainty Quantification in graphs of functions through sample reweighting

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CERMICS¹, IRT SystemX²

Outline of the presentation

Introduction & motivation

Decomposition-based Uncertainty Quantification

One node - A particular weighting scheme based on a Wasserstein distance criterion

Whole graph - Analysis of the general algorithm

Introduction & motivation

Motivation: simulation of complex industrial systems

Complex industrial systems: car, aircraft, rocket ship,...

- From hundreds to ten of thousands engineers working together
- Huge number of requirements to validate, from various sources (safety regulation, environmental regulation,...)
- Uncertainty during the whole design process.

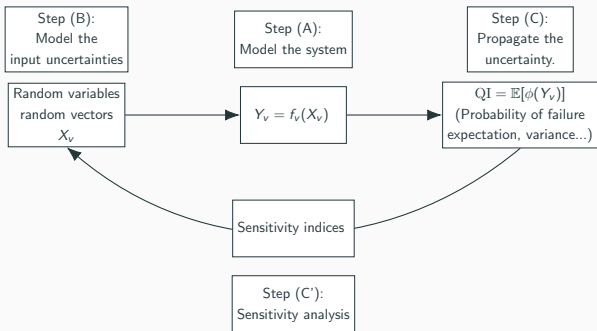
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Need to validate requirements by simulating large parts of systems

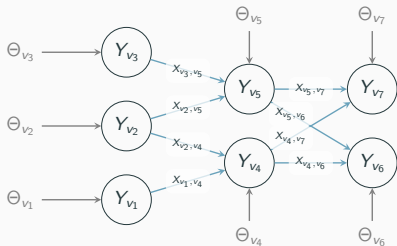
Uncertainty Quantification



Model

- $Y_v = f_v(X_v)$ with X_v and Y_v random variables.
- ABCC' approach
- Probabilistic model of uncertainty

Uncertainty Quantification in complex systems



Graph of computer codes.

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Multidisciplinary system

Each discipline v has

- inputs X_v
- outputs Y_v
- a simulation code f_v s.t

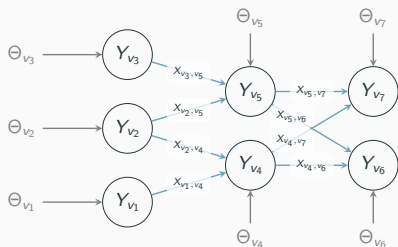
$$Y_v = f_v(X_v)$$

Inputs

X_v composed by

- external variables $X_{u,v}$, for u parents
- internal variables Θ_v

Disciplinary autonomy



Graph of computer codes.

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Goal

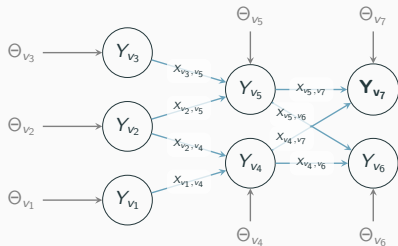
Given $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ and $(\Theta_v, f_v)_{v \in \mathcal{V}}$, compute:

$$\mathbb{E}[\phi(Y_{v_1}, \dots, Y_{v_K})]$$

Industrial constraints

Computations incompatible with graph order.

Disciplinary autonomy



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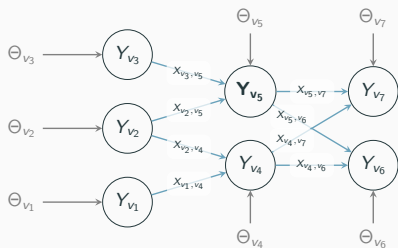
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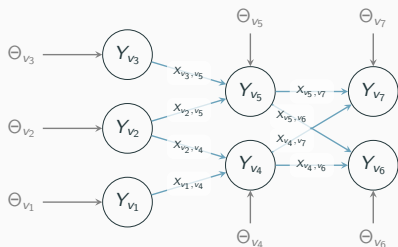
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Classic Monte Carlo forbidden,
need for

Disciplinary autonomy

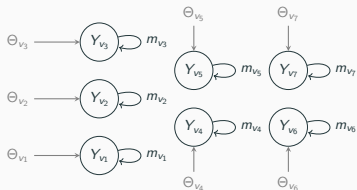
Decomposition-based Uncertainty Quantification

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Disciplinary autonomy

Two phases

Decomposition-based Uncertainty Quantification

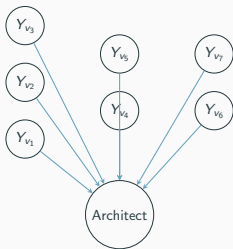
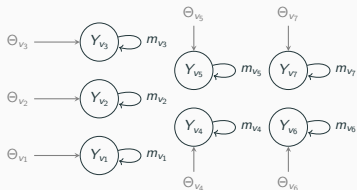


Disciplinary autonomy

Two phases

- *Offline* Computation of f_v , no samples exchange

Decomposition-based Uncertainty Quantification

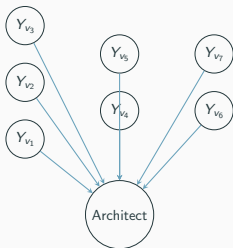
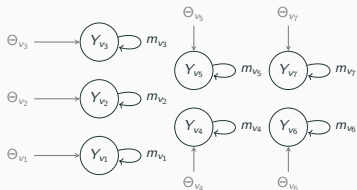


Disciplinary autonomy

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- *Offline* Computation of f_v , no samples exchange
- *Online* Gathering samples, no more f_v

Decomposition-based Uncertainty Quantification



Disciplinary autonomy

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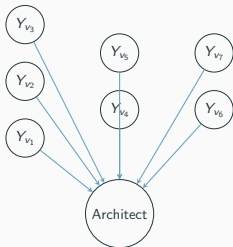
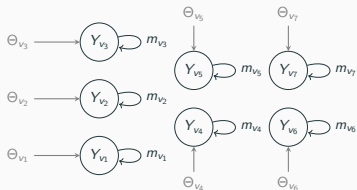
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Question: how to “glue it back” together in the online phase?

Solutions

- Reconstruct each f_v with metamodels or

Decomposition-based Uncertainty Quantification



Amaral, Sergio, Douglas Allaire, and Karen Willcox. "A decomposition-based approach to uncertainty analysis of feed-forward multicomponent systems." *International Journal for Numerical Methods in Engineering* 100.13 (2014): 982-1005.

Disciplinary autonomy

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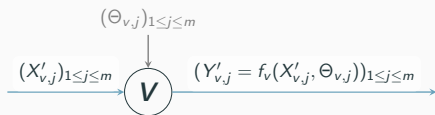
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- **Sample reweighting**

Decomposition-based Uncertainty Quantification

Sample reweighting

Idea, at a given node v :

Decomposition-based Uncertainty Quantification

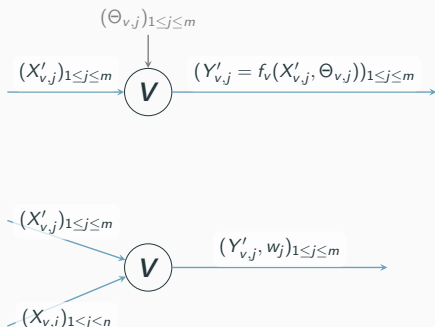


Sample reweighting

Idea, at a given node v :

- *Offline* External input sampled according to a proposal $p_{X'}$, compute $(X'_j, Y'_j)_{1 \leq j \leq m}$.

Decomposition-based Uncertainty Quantification



Sample reweighting

Idea, at a given node v :

- *Offline* External input sampled according to a proposal $p_{X'}$, compute $(X'_j, Y'_j)_{1 \leq j \leq m}$.
- *Online* When a true sample $(X_i)_{1 \leq i \leq n}$ is available, reweight Y'_j to approximate the law $f(X)$

Sample reweighting

Goal

Given two i.i.d samples of law μ_X and $\mu_{X'}$

$$\mathbf{X}_n = (X_i)_{1 \leq i \leq n}$$

$$\mathbf{X}'_m = (X'_j)_{1 \leq j \leq m}$$

Sample reweighting

Goal

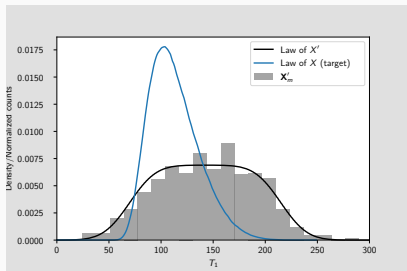
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$$\mathbf{X}_n = (X_i)_{1 \leq i \leq n}$$

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find weights (w_1, \dots, w_m)

Sample reweighting



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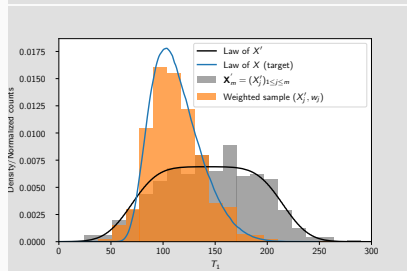
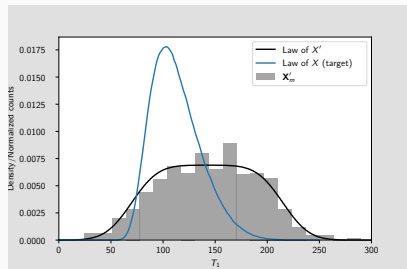
find weights (w_1, \dots, w_m) such that

$$(X'_j, w_j) \stackrel{\text{law}}{\simeq} \mathbf{X}_n$$

ie $\mathbb{E}[\psi(X)] \simeq$

$$1/m \sum_{j=1}^m w_j \psi(X'_j)$$

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One node - A particular weighting scheme based on a Wasserstein distance criterion

Sample reweighting, first idea: importance weighting

$$\int f(x)\mu_X(dx) = \int f(x)\frac{\mu_X}{\mu_{X'}}(x)\mu_{X'}(dx) \simeq \sum_{j=1}^m w_j f(X'_j)$$

with $w_j = \frac{\mu_X}{\mu_{X'}}(X'_j)$.

Two limits:

Sample reweighting, first idea: importance weighting

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Two limits:

- Computing μ_X and $\mu_{X'}$ required.

Only $(X_i)_{i \in \llbracket 1, n \rrbracket}$ $(X'_j)_{j \in \llbracket 1, m \rrbracket}$, not μ_X and $\mu_{X'}$.

\Rightarrow *Density ratio estimation* [1], various methods developed.

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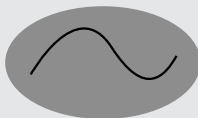
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 \Rightarrow *Density ratio estimation* [1], various methods developed.
- μ_X needs a density w.r.t $\mu_{X'}$ (absolute continuity)

— Support of μ_X
■ Support of $\mu_{X'}$

Assumption not verified in
practice



Another approach: reinterpretation with empirical measures

Empirical measure on \mathbf{X}_n , weighted empirical measure on \mathbf{X}'_m

$$\hat{\mu}_{\mathbf{X},n} = \frac{1}{n} \sum_{i=1}^n \delta_{X_i}, \quad \hat{\mu}_{\mathbf{X}',m}^{\mathbf{w}} = \sum_{j=1}^m w_j \delta_{X'_j}$$

with $\sum_{j=1}^m w_j = m$.

$$\langle \hat{\mu}_{\mathbf{X},n}, \phi \circ f \rangle \xrightarrow{n \rightarrow +\infty} \mathbb{E}[\phi(f(X))](L.L.N)$$

Minimization of the distance between empirical measures

$$\mathbf{w}^* = \underset{\sum w_i = 1, w_i \geq 0}{\operatorname{argmin}} \quad d \left(\hat{\mu}_{\mathbf{X},n}, \hat{\mu}_{\mathbf{X}',m}^{\mathbf{w}} \right)$$

Choice of distance

Wasserstein distances of order q [2]

μ and ν two probability measures on \mathbb{R}^d , with first q moments.
Wasserstein distance

$$W_q(\mu, \nu) = \inf \left\{ \int_{\mathbb{R}^d \times \mathbb{R}^d} |x - x'|^q d\gamma(x, x') : \gamma \in \Pi(\mu, \nu) \right\}^{1/q},$$

$\Pi(\mu, \nu)$: proba measures on $\mathbb{R}^d \times \mathbb{R}^d$ with marginals μ and ν .

Optimal weights. (Reygner J., T.A 2020)

Let the optimal weights be $\mathbf{w}^* = \underset{\sum w_j=1, w_j \geq 0}{\operatorname{argmin}} W_q \left(\hat{\mu}_{X,n}, \hat{\mu}_{X',m}^{\mathbf{w}} \right)$.

Then

$$w_j^* = \frac{1}{n} \sum_{i=1}^n \mathbb{1}_{\{X'_j = \operatorname{NN}(X_i)\}}.$$

Consistency of the weighting scheme

A1. Support condition

We have $\text{Supp}(\mu_X) \subset \text{Supp}(\mu_{X'})$.

A2. Min-integrability

There exists an integer $m_0 \geq 1$ such that

$$\mathbb{E} \left[\min_{j \in \llbracket 1, m_0 \rrbracket} |X'_j| \right] < +\infty.$$

Theorem Consistency (Reygnier J., T. A. , 2020)

Let (A1) and (A2) hold. For all $q \in [1, +\infty)$ s.t $\mathbb{E}[|X|^q] < +\infty$, then

$$\lim_{m \rightarrow +\infty} \mathbb{E} \left[W_q^q \left(\hat{\mu}_{X,n}, \hat{\mu}_{X',m}^{w,*} \right) \right] = 0,$$

uniformly in n .

A3: Strong support condition [3]

There exists an open set $U \subset \mathbb{R}^d$ which contains $\text{Supp}(\mu_X)$ and such that:

1. the measure $\mu_{X'}(\cdot \cap U)$ has a density $p_{X'}$ with respect to the Lebesgue measure; $p_{X'}$ is continuous and positive on U ;
2. there exist $\kappa \in (0, 1]$ and $r_\kappa > 0$ such that, for any $x \in U$, for any $r \in [0, r_\kappa]$,

$$\mathbb{P}(X' \in B(x, r)) \geq \kappa p_{X'}(x) v_d r^d.$$

A4: Moments

$$\mathbb{E} \left[\frac{1 + |X|^q}{p_{X'}(X)^{q/d}} \right] < +\infty.$$

[3] Sébastien Gadat, Thierry Klein, Clément Marteau, et al. Classification in general finite dimensional spaces with the k-nearest neighbor rule. The Annals of Statistics, 44(3):982–1009, 2016.

Theorem Convergence rates (Reygner J., T. A. , 2020)

Let Assumptions A2 and A3 hold, and let $q \in [1, +\infty)$ be such that Assumption A4 holds. Then we have

$$\lim_{m \rightarrow +\infty} m^{q/d} \mathbb{E} \left[W_q^q \left(\hat{\mu}_{X,n}, \hat{\mu}_{X',m}^{\mathbf{w}^*} \right) \right] = c_{q,d} \mathbb{E} \left[\frac{1}{p_{X'}(X)^{q/d}} \right].$$

- Curse of the dimensionality $m^{-q/d}$ (similar NNR)
- Can be reinterpreted in terms of NNR under covariate shift

$$\mathbb{E} \left[W_q^q \left(\hat{\mu}_{X,n}, \hat{\mu}_{X',m}^{\mathbf{w}^*} \right) \right] = \mathbb{E} \left[|X - \text{NN}_{\mathbf{X}'_m}(X)|^q \right]$$

Reygner, Julien, and T.A. . "Reweight samples under covariate shift using a Wasserstein distance criterion."

arXiv preprint arXiv:2010.09267 (2020).

Conclusion of the part

Results

For a given node, a weighting method has been analyzed

- Weights given by minimization of Wasserstein distance
- Weights expressed in terms of 1-Nearest Neighbor
- Expected rate of convergence (under appropriate assumptions)

$$\begin{aligned}\mathbb{E}[W_q^q(\mu_X, \hat{\mu}_{X',m}^{\mathbf{w}^*})] &\leq \mathbb{E}[W_q^q(\mu_X, \hat{\mu}_{X,n})] + \mathbb{E}[W_q^q(\hat{\mu}_{X,n}, \hat{\mu}_{X',m}^{\mathbf{w}^*})] \\ &= O(n^{-q/d}) + O(m^{-q/d})\end{aligned}$$

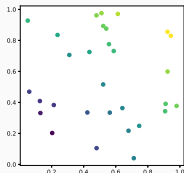
[4] + Reygner J., T. A.(2020)

- Application to estimation of a quantity of interest

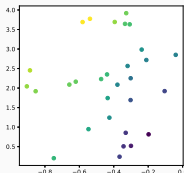
[4] Fournier, Nicolas, and Arnaud Guillin. "On the rate of convergence in Wasserstein distance of the empirical measure." *Probability Theory and Related Fields* 162.3 (2015): 707-738.

Whole graph - Analysis of the general algorithm

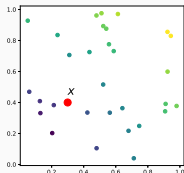
Weighted Linear Approximation Method



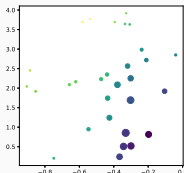
Sample X'_j



$Y'_j = f(X'_j, \Theta_j)$



New input
 $x = (0.3, 0.4)$



Gives weights
to Y'_j

Question

What is a weighting method in general?

Weighted Linear Approximation Method (WLAM) (Reygner J., T. A. 2021)

- $\mathbf{S}_m = (X'_j, Y'_j)_{1 \leq j \leq m}$
- $\mathbf{W}_m = (W_j)_{1 \leq j \leq m} :$
 $(E \times F)^m \times E \rightarrow [0, +\infty)^m$
s.t. $\forall \mathbf{S}_m \in (E \times F)^m, x \in E,$

$$\sum_{j=1}^m W_j(\mathbf{S}_m, x) = 1.$$

Approximate image measure associated to W_m

$$\hat{\ell}_m(x, dy) = \sum_{j=1}^m W_j(\mathbf{S}_m, x) \delta_{Y'_j}(dy)$$

approximates the law of Y' conditioned to $X' = x$ (Markov kernel)

\mathfrak{B} -consistency (definition)

A WLAM is consistent i.i.f for all $\phi \in \mathfrak{B}$

$$\begin{aligned} \lim_{m \rightarrow +\infty} \sum_{j=1}^m W_j(\mathbf{S}_m, x) \phi(Y'_j) &= \mathbb{E}[\phi(Y') | X' = x] \\ &= \mathbb{E}[\phi(f(x, \Theta_v))], \end{aligned}$$

in probability.

Examples of WLAMs

- k_m -Nearest-neighbor:

$$W_j(\mathbf{S}_m, x) = 1/k_m \sum_{j'=1}^{k_m} \mathbb{1}_{\{X_{j'} = \text{NN}^{(k_m)}(x)\}}$$

\mathfrak{B} : ϕ bounded for which $x \mapsto \mathbb{E}[\phi(f(x, \Theta))]$ is Lipschitz-continuous (previous section).

- Nadayara-Watson:

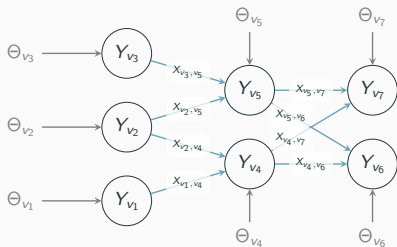
$$W_j(\mathbf{S}_m, x) = K_{j,m}(x) / (\sum_{k=1}^m K_{k,m}(x))$$

\mathfrak{B} : ϕ bounded for which $x \mapsto \mathbb{E}[\phi(f(x, \Theta))]$ is continuous.

- Regression tree: $W_j(\mathbf{S}_m, x) = 1/m(x) \mathbb{1}_{\{X_{j'} \in L(x)\}}$

$W_j(\mathbf{S}_m, x)$ needs not to be linear in x .

Back to the whole graph



The graph is a Bayesian Network

$(\mathcal{G}, (Y_v)_{v \in \mathcal{V}})$ verifies a Markov Property.

Each node is conditionally independent from its nondescendants, given its direct parents.

Proof:

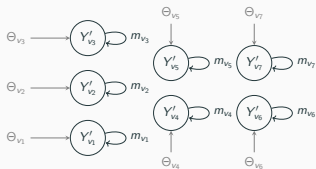
$$Y_v = f_v((X_{u,v})_{u \in \text{Par}(v)}, \Theta_v)$$

Factorization property of a B.N

$$\mu_{\mathcal{V}}((dy_v)_{v \in \mathcal{V}}) = \prod_{v \in \mathcal{V}} \ell_v(y_v, (dy_u)_{u \in \text{Par}(v)})$$

Final algorithm (Reygner J.
T.A, 2021)

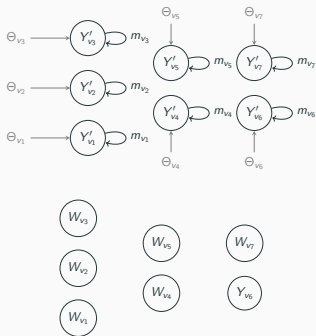
Propagation



Final algorithm (Reygner J. T.A, 2021)

1. *Offline* Computation of $(X'_v, f_v(X'_v, \Theta_v))$

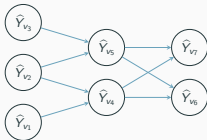
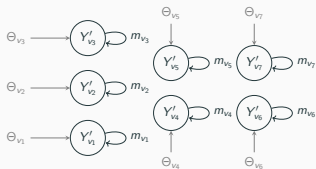
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Final algorithm (Reygner J. T.A, 2021)

1. *Offline* Computation of $(X'_v, f_v(X'_v, \Theta_v))$
2. *Online 1* Weighting and choice of a WLAM at each node.

Propagation



[5] Koller, D., & Friedman, N. (2009). Probabilistic graphical models: principles and techniques. MIT press.

Final algorithm (Reygnier J. T.A, 2021)

1. *Offline* Computation of $(X'_v, f_v(X'_v, \Theta_v))$
2. *Online 1* Weighting and choice of a WLAM at each node.
3. *Online 2* Propagation - Replace each ℓ_v by $\hat{\ell}_{v, m_v}$.

$$\begin{aligned} \mu_{\mathcal{V}}((dy_v)_{v \in \mathcal{V}}) &\simeq \hat{\mu}((dy_v)_{v \in \mathcal{V}}) \\ &= \prod_{v \in \mathcal{V}} \hat{\ell}_v(y_v, (dy_u)_{u \in \text{Par}(v)}) \end{aligned}$$

Discrete Bayesian Network,
Classic propagation methods[5].

Consistency (Reygner J., T.A 2021)

Assume that $\phi((y_v)_{v \in \mathcal{V}})$ is bounded continuous and at each v , the WLAM is \mathfrak{B} -consistent, for a compatible family, then

$$\lim_{m_{v_1} \rightarrow +\infty} \cdots \lim_{m_{v_n} \rightarrow +\infty} \langle \phi, \hat{\mu}((dy_v)_{v \in \mathcal{V}}) \rangle = \mathbb{E}[\phi((Y_v)_{v \in \mathcal{V}})],$$

with the m_{v_1}, \dots, m_{v_n} chosen in an order compatible with the graph.

Three key points

1. A graph of composition of functions is a Bayesian Network $(\mathcal{G}, \mathcal{L}(Y_v | (X_{u,v})_{u \in \text{Par}(v)}))$.

Conditional Probability Tables (C.P.T) $\mathcal{L}(Y_v | (X_{u,v})_{u \in \text{Par}(v)})$ given by

$$Y_v = f((X_{u,v})_{u \in \text{Par}(v)}, \Theta_v)$$

2. Some weighting methods (NNR, Nadayara-Watson, regression trees...) approximate naturally a C.P.T $\hat{\mathcal{L}}(Y_v | X_{u,v})$
3. The Bayesian network $(\mathcal{G}, \hat{\mathcal{L}}(Y_v | (X_{u,v})_{u \in \text{Par}(v)}))$ is discrete (computations available). Its law approximates $(\mathcal{G}, \mathcal{L}(Y_v | (X_{u,v})_{u \in \text{Par}(v)}))$. The weights can be computed numerically.

- Rates of convergences *in the graph* + a posteriori error estimates.
- Efficient computations in Bayesian inference (weights propagation). Sparse propagation?
- Application to other problems than disciplinary autonomy?
- Numerical benchmark of various WLAMs methods, in terms of law approximation.

Resources

- Reygner, Julien, and Touboul, Adrien. "Reweighting samples under covariate shift using a Wasserstein distance criterion." arXiv preprint arXiv:2010.09267 (2020).
- Reygner, Julien "Theoretical analysis and numerical methods for conservation laws, metastability and uncertainty propagation", HDR, (2021), to be defended.
- Touboul, Adrien "Model of margin, margin sensitivity analysis and uncertainty quantification in graphs of functions in complex industrial systems", PhD Thesis (2021), to be defended.